

## 16 Velocity, v1 and v2

### 16.1 Sensor

The airfoil probes are constructed in the manner developed by *Oakey* [1977] and shown in Fig. 34. One end of a bimorph beam is potted directly in hard epoxy, and the remainder

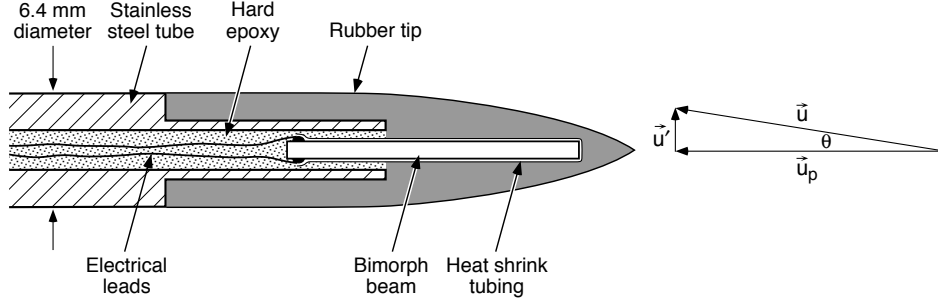


Figure 34: Schematic of airfoil probe used on MMP. For MMP, the probe velocity is the fall rate,  $w$ , and  $u'$  is any horizontal velocity relative to the MMP.

is encased in the soft rubber tip. The beams have high impedance, with resistances of about  $10^{13} \Omega$ , and capacitances of  $C_S \approx 1000$  pF. Bending a beam in the direction of its sensitive axis produces a voltage. *Osborn and Crawford* [1980] describe the probes and their sensitivities. Each AMP carries two airfoils, both oriented with their sensitive axis in the same direction so their outputs can be compared during data editing; impacts of plankton on the probes are major causes of noise, and few impacts are simultaneous on both probes.

The rubber tips are made with parabolic cross-sections to provide constant lift for velocities  $u'$  parallel to the sensitive axis. The output voltage is

$$E_0(t) = S_v \left( \frac{V^2}{2g} \right) \frac{u'(t)}{V} \quad [V], \quad (66)$$

where  $S_v$  is the probe sensitivity, and  $g$  is the gravitational constant. Typical sensitivities are  $S_v = 18$  to 30 volts per meter.

The probes must be calibrated before and after cruises. This consists of measuring  $C_S$  with a precision capacitance meter and determining  $S_v$  using *Oakey's* procedure of placing them in a steady water jet having speed  $V$ . Slowly oscillating the probes creates a cross-velocity by changing the angle of attack,  $\theta$ . Owing to the small angles,  $u'(t)/V \approx \sin \theta(t)$ . In practice,  $\theta(t)$  and  $E_0(t)$  are sinusoidal, and  $S_v$  is determined from their peak amplitudes. As shown below, the probe capacitance,  $C_S$ , also affects gain and must be measured. The nominal capacitance is 1000 pF. Probe sensitivities and capacitances measured before and after the cruise typically differ less than 15%.

*Oakey* [1977] estimates the dynamic response of the airfoil probes as

$$H_{\text{Oakey}}^2(f, w) = \frac{1}{1 + (\lambda_c f/w)^2}, \quad \phi_{\text{Oakey}}(f, w) = \quad (67)$$

with  $\lambda_c = 0.02$  m and  $k_3 = f/w$ , which is the vertical wavenumber in cycles per meter (cpm). Based on laboratory comparisons with a laser Doppler velocimeter, *Ninnis* [1984] gives the transfer function as

$$H_{\text{Ninnis}}^2(f, w) = A_0 + x(A_1 + x(A_2 + x(A_3 + xA_4))) , \quad (68)$$

where  $x \equiv f/(wK_0)$ . It is meant to be used only to 100 cpm, corresponding to 60 Hz at a typical fall rate of  $0.6 \text{ m s}^{-1}$ . The parameters are given in Table 13, and both probe responses are shown in Figure 35. We use the Oakey version.

Parameter	Value
$K_0$	140.0
$A_0$	1.000
$A_1$	-0.165
$A_2$	-4.763
$A_3$	5.900

Table 13: Parameter values for Ninnis’s representation of the airfoil transfer function.

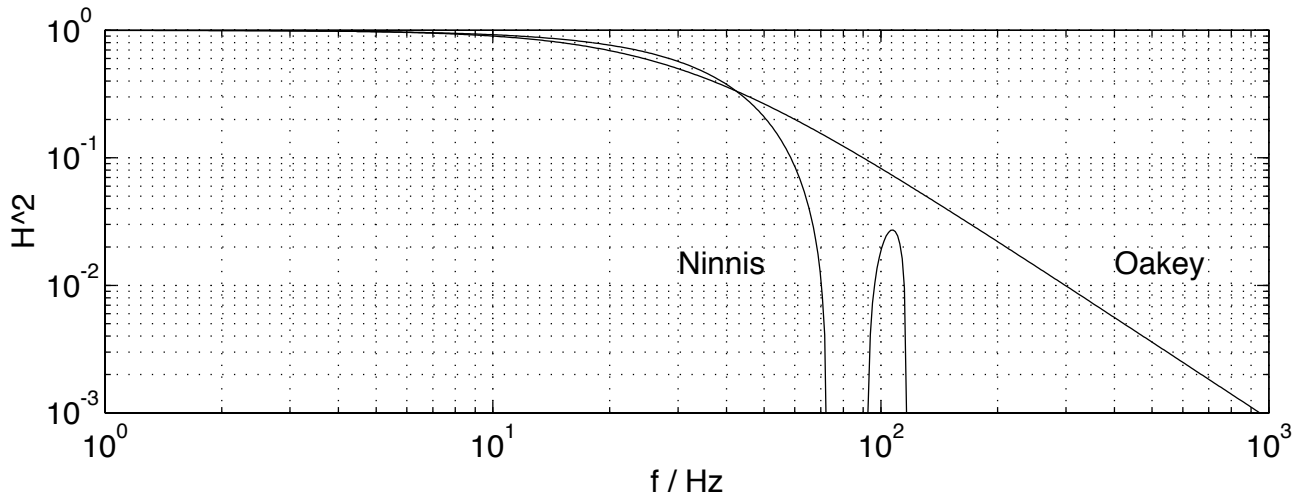


Figure 35: Transfer functions of the airfoil probe, with  $w = 0.6 \text{ m s}^{-1}$ .

## 16.2 Electronics

The airfoil output voltage,  $E_0$  is fed into three sequential circuits that buffer, differentiate, and amplify the signal (Figure 36). Circuit parameters are listed in Table 14.

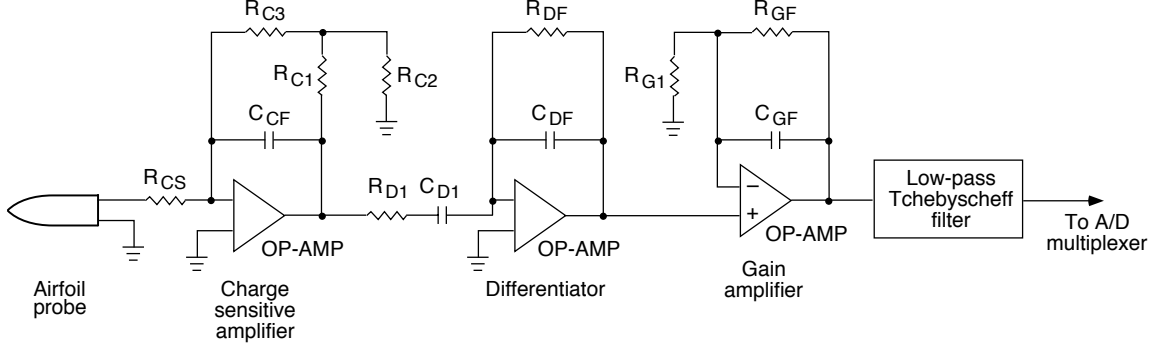


Figure 36: Schematic of airfoil circuits. The probe capacitance,  $C_S$  is between  $R_{CS}$  and common.

Component	Value	Component	Value
$R_{C1}$	$1 \times 10^6 \Omega$	$R_{DF}$	$4.75 \times 10^5 \Omega$
$R_{C2}$	$3.01 \times 10^3 \Omega$	$C_{DF}$	$8.2 \times 10^{-10} \text{ F}$
$R_{C3}$	$1 \times 10^7 \Omega$	$R_{G1}$	$1.21 \times 10^4 \Omega$
$C_{CF}$	$1 \times 10^{-9} \text{ F}$	$R_{GF}$	$3.74 \times 10^4 \Omega$
$R_{D1}$	$2.37 \times 10^3 \Omega$	$R_{CS}$	$1 \times 10^5 \Omega$
$C_{D1}$	$3.3 \times 10^{-7} \text{ F}$		

Table 14: Values of circuit components used with the airfoil probes.

The first stage is a charge-sensitive amplifier whose output matches its input voltage while supplying the current needed by the second stage. The power transfer function of the charge amplifier is

$$H_{ca}^2(f, C_S) = \frac{(C_S/C_{CF})^2(f/f_L)^2}{(1 + (f/f_L)^2)(1 + (f/f_H)^2)} \quad (69)$$

where

$$R_f \equiv \frac{R_{C1}R_{C3}}{R_{C2}} = 3.32 \times 10^9 \Omega \quad , \quad f_L \equiv (2\pi R_f C_{CF})^{-1} = 0.0479 \text{ Hz} \quad , \quad (70)$$

and

$$f_H = (2\pi R_{CS} C_S)^{-1} \approx 1592 \text{ [Hz]} \quad . \quad (71)$$

The response is unity at frequencies resolved by the airfoil probes and rolls off at lower and higher frequencies. The high-frequency rolloff is so much larger than frequencies of interest, that the term can be treated as a constant rather than being evaluated with  $C_S$  for each probe. We do not have an expression for phase as a function of frequency.

The second stage differentiates frequencies less than 100 Hz,

$$H_{diff}^2(f) = \frac{K^2 f^2}{(f_1^2 + f^2)(f_2^2 + f^2)} \quad , \quad \phi_{diff}(f) = \tan^{-1} \left( \frac{f_1 f_2 - f^2}{f(f_1 + f_2)} \right) \quad , \quad (72)$$

where

$$K \equiv (2\pi R_{D1} C_{DF})^{-1} = 81,895 \text{ Hz} , \quad (73)$$

and

$$f_1 \equiv (2\pi R_{D1} C_{D1})^{-1} = 203.5 \text{ Hz} , \quad f_2 \equiv (2\pi R_{DF} C_{DF})^{-1} = 408.6 \text{ Hz} . \quad (74)$$

It is plotted in Figure 37.

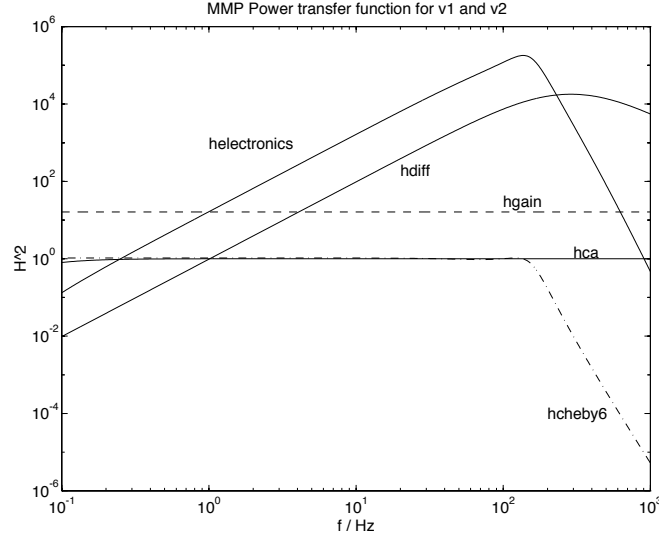


Figure 37: Power transfer functions for v1 and v2 electronics.

The third stage sets the gain with

$$H_{\text{gain}}^2(f) = \left(1 + \frac{R_{GF}}{R_{G1}}\right)^2 = 16.74 , \quad \phi_{\text{gain}}(f) = 0 . \quad (75)$$

A 6-pole low-pass type 1 Tchebyscheff filter attenuates signals to minimize aliasing. The magnitude-squared response is given by (10).

The net electronic transfer function is the product of the seperate components

$$H_{\text{electronics}}^2(f, C_S) = H_{\text{ca}}^2(f, C_S) H_{\text{diff}}^2(f) H_{\text{gain}}^2 \quad (76)$$

$$\phi_{\text{electronics}}(f) = \phi_{\text{hca}} + \phi_{\text{hdiff}} \quad (77)$$

It is plotted in Figure 37.

The total transfer function is

$$H_{\text{total}}^2(f, S_v, C_S, w, f_c) = \left(\frac{w S_v}{2g}\right)^2 H_{\text{electronics}}^2(f) H_{\text{Oakey}}^2(f, w) H_{\text{Tch}}^2(f, f_c) \quad [\text{volts}^2 (\text{m/s})^{-2}] . \quad (78)$$

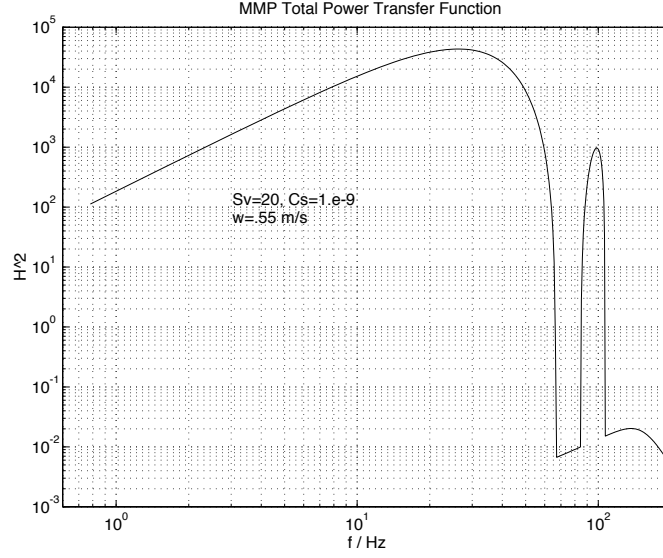


Figure 38: Total system power transfer function. Spectrum of raw v1 or v2 record in volts is divided by this to form a velocity spectrum in  $\text{m}^2 \text{s}^{-1} \text{Hz}^{-1}$ .

The scaling factor,  $(wS_v/2g)^2$ , comes from (66) and is about 0.58 for typical values of  $S_v = 25$ ,  $C_s = 1,000 \text{ pF}$ , and  $w = 0.6 \text{ m s}^{-1}$ . It is shown in Figure 38.

Before 30 Jan 1995, the Tchebyscheff anti-alias filter had  $f_c = 150 \text{ Hz}$ . On that day  $f_c$  was changed to 100 Hz. Spectra of raw data in  $\text{volts}^2 \text{Hz}^{-1}$  are divided by  $H_{\text{total}}^2$  to obtain velocity spectra in  $\text{m}^2 \text{s}^{-1} \text{Hz}^{-1}$ .

## 16.3 Data Conversion

### 16.3.1 Spectra

The power spectrum of recorded signals, converted to volts, is

$$\Phi_R(f) = \frac{\Phi_u(k_3)}{w} H_{\text{electronics}}^2(f, C_s) H_{\text{Tch}}^2(f, f_c) H_{\text{Oakey}}^2(f, w) \left( \frac{S_v w}{2g} \right)^2 \quad [\text{V}^2 \text{Hz}^{-1}] . \quad (79)$$

Inverting gives the oceanic velocity spectrum,

$$\Phi_u(k_3) = \frac{w \Phi_R(f)}{H_{\text{electronics}}^2(f, C_s) H_{\text{Tch}}^2(f, f_c) H_{\text{Oakey}}^2(f, w)} \quad (80)$$

The spectrum of vertical shear is

$$\Phi_{\partial u / \partial z}(k_3) = (2\pi k_3)^2 \Phi_u(k_3) \quad [\text{s}^{-2} \text{cpm}^{-1}] . \quad (81)$$

The rate of viscous dissipation of turbulent kinetic energy,  $\epsilon$ , is obtained by integrating the shear spectrum

$$\epsilon = 7.5\nu(s, T, P) \int_{k_0}^{k_u} \Phi_{\partial u/\partial z}(k_3) dk_3 \quad [\text{W kg}^{-1}] , \quad (82)$$

where  $\nu(s, T, P)$  is the kinematic viscosity, and  $k_0$  and  $k_u$  are the lower and upper cutoffs determined by record length and the character of the data, respectively. Variations in  $\nu$  are large enough that it should be evaluated at in-situ conditions.

The dissipation spectrum,

$$\phi_{\text{diss}} = k_3 \Phi_{\partial u/\partial z}(k_3) \quad [\text{s}^{-2}] , \quad (83)$$

shows the relative contributions of different wavenumbers to  $\epsilon$  if plotted with a logarithmic  $k_3$  axis and a linear abscissa.

## 16.4 Observed Characteristics

## BIBLIOGRAPHY

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